Exploiting consumers flexibilities *via* a Demand Response mecanism: Decentralized Nash Computation

P. Jacquot 1,2 O.Beaude 1 S. Gaubert 2 N.Oudjane 1

¹EDF Lab

²Inria and CMAP, École Polytechnique

June 30, 2017



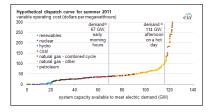
Réseau Optimisation EDF Lab, Paris-Saclay



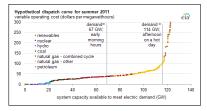
Paulin J. (EDF - Inria)

Demand Response - Decentralized

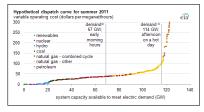
June 30, 2017 1 / 19



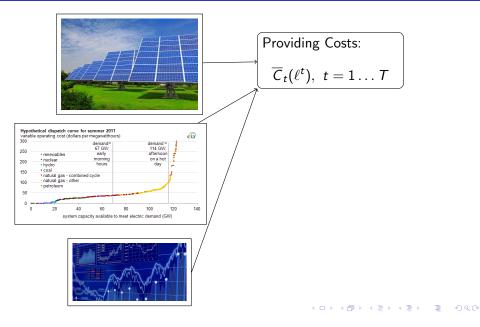


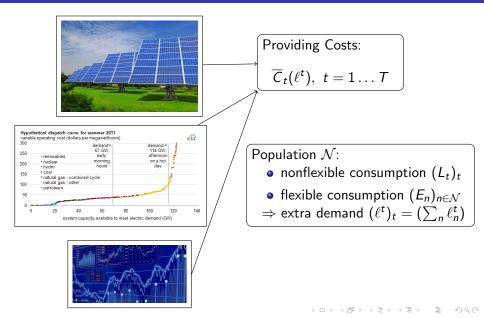


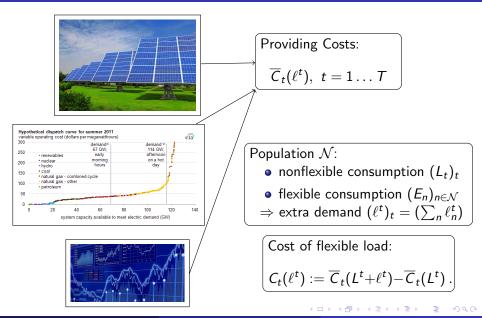


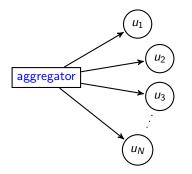




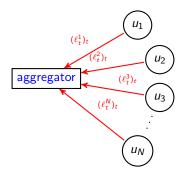




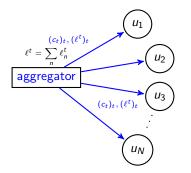




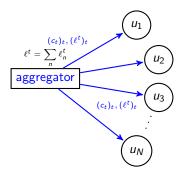
 One distributor/aggregator d provides a set N of N residential consumers



- One distributor/aggregator d provides a set N of N residential consumers
- Consumers send their desired consumption profiles (l^t_n)_t,



- One distributor/aggregator d provides a set N of N residential consumers
- Consumers send their desired consumption profiles (l^t_n)_t,
- Aggregator broadcast costs and aggregated load (l^t)_t,



- One distributor/aggregator d provides a set N of N residential consumers
- Consumers send their desired consumption profiles (l^t_n)_t,
- Aggregator broadcast costs and aggregated load (l^t)_t,
- Consumers eventually reach an equilibrium.

$$\sum_{t\in\mathcal{T}}\ell_n^t = E_n,\tag{1b}$$

$$\sum_{t \in \mathcal{T}} \ell_n^t = E_n, \qquad (1b)$$
$$\underline{\ell}_n^t \le \ell_n^t \le \overline{\ell}_n^t, \forall t \in \mathcal{T} . \quad (1c)$$

$$\min_{\ell_n \in \mathbb{R}^T} \quad b_n(\ell_n, \ell_{-n})$$
(1a)
s.t.
$$\sum_{t \in \mathcal{T}} \ell_n^t = E_n,$$
(1b)
$$\underline{\ell}_n^t \le \ell_n^t \le \overline{\ell}_n^t, \forall t \in \mathcal{T} .$$
(1c)

Paulin J. (EDF - Inria)

June 30, 2017 4 / 19

$$\min_{\ell_n \in \mathbb{R}^T} \quad b_n(\ell_n, \ell_{-n})$$
(1a)
s.t.
$$\sum_{t \in \mathcal{T}} \ell_n^t = E_n,$$
(1b)
$$\underline{\ell}_n^t \le \ell_n^t \le \overline{\ell}_n^t, \forall t \in \mathcal{T} .$$
(1c)

where b_n is the dynamic price for user n (bill), taken as:

$$\min_{\ell_n \in \mathbb{R}^T} \quad b_n(\ell_n, \ell_{-n})$$
(1a)
s.t.
$$\sum_{t \in \mathcal{T}} \ell_n^t = E_n,$$
(1b)
$$\underline{\ell}_n^t \le \ell_n^t \le \overline{\ell}_n^t, \forall t \in \mathcal{T} .$$
(1c)

where b_n is the dynamic price for user n (bill), taken as:

Definition (Daily Prop.)
$$b_n^{\text{DP}}(\ell) = \frac{E_n}{\sum_m E_m} \sum_{t \in \mathcal{T}} C_t(\ell^t)$$

Paulin J. (EDF - Inria)

$$\min_{\ell_n \in \mathbb{R}^T} \quad b_n(\ell_n, \ell_{-n})$$
(1a)
s.t.
$$\sum_{t \in \mathcal{T}} \ell_n^t = E_n,$$
(1b)
$$\underline{\ell}_n^t \le \ell_n^t \le \overline{\ell}_n^t, \forall t \in \mathcal{T} .$$
(1c)

where b_n is the dynamic price for user n (bill), taken as:

Definition (Daily Prop.)

$$b_n^{\text{DP}}(\ell) = \frac{E_n}{\sum_m E_m} \sum_{t \in \mathcal{T}} C_t(\ell^t)$$
Definition (Hourly Prop.)

$$b_n^{\text{HP}}(\ell) = \sum_{t \in \mathcal{T}} \frac{\ell_n^t}{\ell^t} C_t(\ell^t)$$

Paulin J. (EDF - Inria)

Demand Response - Decentralized

$$\min_{\ell_n \in \mathbb{R}^{\mathcal{T}}} \quad b_n(\ell_n, \ell_{-n})$$
(1a)
s.t.
$$\sum_{t \in \mathcal{T}} \ell_n^t = E_n,$$
(1b)
$$\underline{\ell}_n^t \le \ell_n^t \le \overline{\ell}_n^t, \forall t \in \mathcal{T} .$$
(1c)

where b_n is the dynamic price for user n (bill), taken as:

Definition (Daily Prop.)

$$b_n^{\text{DP}}(\ell) = \frac{E_n}{\sum_m E_m} \sum_{t \in \mathcal{T}} C_t(\ell^t)$$
Definition (Hourly Prop.)

$$b_n^{\text{HP}}(\ell) = \sum_{t \in \mathcal{T}} \frac{\ell_n^t}{\ell^t} C_t(\ell^t)$$

ightarrow N-person minimization game $\mathcal{G} := \left(\mathcal{N}, \mathcal{L}, (b_n)_n
ight)$

Paulin J. (EDF - Inria)

 $ightarrow b_n(\ell_n,\ell_{-n})$ cost of consumer n

Definition

The profile $(\hat{\ell}_n)_n$ is a Nash Equilibrium *IFF* for all player *n*, for all possible admissible profile (strategy) ℓ_n :

$$b_n(\hat{\ell}_n, \hat{\ell}_{-n}) \leq b_n(\ell_n, \hat{\ell}_{-n}) \ \iff \hat{\ell}_n = \operatorname*{argmin}_{\ell_n \in \mathcal{L}_n} b_n(\ell_n, \hat{\ell}_{-n}).$$

Paulin J. (EDF - Inria)

 $\rightarrow b_n(\ell_n, \ell_{-n})$ cost of consumer n

Definition

The profile $(\hat{\ell}_n)_n$ is a Nash Equilibrium *IFF* for all player *n*, for all possible admissible profile (strategy) ℓ_n :

$$b_n(\hat{\ell}_n, \hat{\ell}_{-n}) \leq b_n(\ell_n, \hat{\ell}_{-n}) \ \iff \hat{\ell}_n = \operatorname*{argmin}_{\ell_n \in \mathcal{L}_n} b_n(\ell_n, \hat{\ell}_{-n}).$$

Remark: Existence and Uniqueness are not general!

 $\rightarrow b_n(\ell_n, \ell_{-n})$ cost of consumer n

Definition

The profile $(\hat{\ell}_n)_n$ is a Nash Equilibrium *IFF* for all player *n*, for all possible admissible profile (strategy) ℓ_n :

$$b_n(\hat{\ell}_n, \hat{\ell}_{-n}) \leq b_n(\ell_n, \hat{\ell}_{-n}) \ \iff \hat{\ell}_n = \operatorname*{argmin}_{\ell_n \in \mathcal{L}_n} b_n(\ell_n, \hat{\ell}_{-n}).$$

Remark: Existence and Uniqueness are not general! Depends on the structure of b_n 's...

 $\rightarrow b_n(\ell_n, \ell_{-n})$ cost of consumer n

Definition

The profile $(\hat{\ell}_n)_n$ is a Nash Equilibrium *IFF* for all player *n*, for all possible admissible profile (strategy) ℓ_n :

$$b_n(\hat{\ell}_n, \hat{\ell}_{-n}) \leq b_n(\ell_n, \hat{\ell}_{-n}) \ \iff \hat{\ell}_n = \operatorname*{argmin}_{\ell_n \in \mathcal{L}_n} b_n(\ell_n, \hat{\ell}_{-n}).$$

Remark: Existence and Uniqueness are not general! Depends on the structure of b_n 's...

Equilibrium \iff no one has any interest to change!

We want an algorithm to compute the equilibrium profile:

 decentralized: for privacy reasons and dimension of the global problem, We want an algorithm to compute the equilibrium profile:

- decentralized: for privacy reasons and dimension of the global problem,
- asynchronous: it would not be possible to synchronize efficiently if local optimizations are performed,

We want an algorithm to compute the equilibrium profile:

- decentralized: for privacy reasons and dimension of the global problem,
- asynchronous: it would not be possible to synchronize efficiently if local optimizations are performed,
- **§ fast**: the equilibrium may have to be recomputed.

while $\ell^{(k)} \neq \ell^{(k+1)}$ do

while
$$\ell^{(k)} \neq \ell^{(k+1)}$$
 do
for $n \in \{1, 2, ..., N\}$ do
Update *n*'s strategy as:
 $\ell_n^{(k+1)} \in \underset{\mathbf{x} \in \mathcal{L}_n}{\operatorname{argmin}} b_n \left(\ell_1^{(k+1)}, \dots, \ell_{n-1}^{(k+1)}, \mathbf{y}, \ell_{n+1}^{(k)}, \dots, \ell_N^{(k)}\right);$

while
$$\ell^{(k)} \neq \ell^{(k+1)}$$
 do
for $n \in \{1, 2, ..., N\}$ do
Update *n*'s strategy as:
 $\ell_n^{(k+1)} \in \underset{\mathbf{x} \in \mathcal{L}_n}{\operatorname{argmin}} b_n \left(\ell_1^{(k+1)}, \dots, \ell_{n-1}^{(k+1)}, \mathbf{y}, \ell_{n+1}^{(k)}, \dots, \ell_N^{(k)} \right)$;
Go to next cycle $k \leftarrow k + 1$;

while
$$\ell^{(k)} \neq \ell^{(k+1)}$$
 do
for $n \in \{1, 2, ..., N\}$ do
Update *n*'s strategy as:
 $\ell_n^{(k+1)} \in \underset{\mathbf{x} \in \mathcal{L}_n}{\operatorname{argmin}} b_n \left(\ell_1^{(k+1)}, \dots, \ell_{n-1}^{(k+1)}, \mathbf{y}, \ell_{n+1}^{(k)}, \dots, \ell_N^{(k)}\right)$;
Go to next cycle $k \leftarrow k + 1$;

 ℓ is a fixed point of a cycle of BRD $\iff \ell$ is a NE!

while
$$\ell^{(k)} \neq \ell^{(k+1)}$$
 do
for $n \in \{1, 2, ..., N\}$ do
Update *n*'s strategy as:
 $\ell_n^{(k+1)} \in \underset{\mathbf{x} \in \mathcal{L}_n}{\operatorname{argmin}} b_n \left(\ell_1^{(k+1)}, \dots, \ell_{n-1}^{(k+1)}, \mathbf{y}, \ell_{n+1}^{(k)}, \dots, \ell_N^{(k)} \right)$;
Go to next cycle $k \leftarrow k + 1$;

while
$$\ell^{(k)} \neq \ell^{(k+1)}$$
 do
for $n \in \{1, 2, ..., N\}$ do
Update *n*'s strategy as:
 $\ell_n^{(k+1)} \in \underset{\mathbf{x} \in \mathcal{L}_n}{\operatorname{argmin}} b_n \left(\ell_1^{(k+1)}, \dots, \ell_{n-1}^{(k+1)}, \mathbf{y}, \ell_{n+1}^{(k)}, \dots, \ell_N^{(k)} \right)$;
Go to next cycle $k \leftarrow k + 1$;

while
$$\ell^{(k)} \neq \ell^{(k+1)}$$
 do
for $n \in \{1, 2, ..., N\}$ do
Update *n*'s strategy as:
 $\ell_n^{(k+1)} \in \underset{\mathbf{x} \in \mathcal{L}_n}{\operatorname{argmin}} b_n \left(\ell_1^{(k+1)}, \dots, \ell_{n-1}^{(k+1)}, \mathbf{y}, \ell_{n+1}^{(k)}, \dots, \ell_N^{(k)} \right)$;
Go to next cycle $k \leftarrow k + 1$;

while
$$\|\boldsymbol{\ell}^{(k)} - \boldsymbol{\ell}^{(k+1)}\| > \varepsilon$$
 do
for $n \in \{1, 2, ..., N\}$ do
Update *n*'s strategy as:
 $\boldsymbol{\ell}_{n}^{(k+1)} \in \underset{\mathbf{x} \in \mathcal{L}_{n}}{\operatorname{argmin}} b_{n} \left(\boldsymbol{\ell}_{1}^{(k+1)}, \ldots, \boldsymbol{\ell}_{n-1}^{(k+1)}, \mathbf{y}, \boldsymbol{\ell}_{n+1}^{(k)}, \ldots, \boldsymbol{\ell}_{N}^{(k)}\right);$
Go to next cycle $k \leftarrow k + 1;$

Convergence with DP billing

Every user solves

$$\min_{\ell_n \in \mathcal{L}_n} \frac{E_n}{E} \sum_{t \in \mathcal{T}} C_t(\ell^t)$$

Image: A 1 → A

Convergence with DP billing

Every user solves

$$\min_{\ell_n \in \mathcal{L}_n} \frac{E_n}{E} \sum_{t \in \mathcal{T}} C_t(\ell^t) \iff \min_{\ell_n \in \mathcal{L}_n} \sum_{t \in \mathcal{T}} C_t(\ell^t)$$

Image: A 1 → A

Convergence with DP billing

Every user solves

$$\min_{\ell_n \in \mathcal{L}_n} \frac{E_n}{E} \sum_{t \in \mathcal{T}} C_t(\ell^t) \iff \min_{\ell_n \in \mathcal{L}_n} \sum_{t \in \mathcal{T}} C_t(\ell^t)$$

Alternate Minimization :

Theorem (Hong et al., 2017)

Alternate minimization on convex function f over N blocks converges linearly. Precisely, after r cycles:

$$f(x^{(r)}) - \min_{x \in \mathcal{X}} f(x) \leq KN^2 \frac{1}{r}$$
.

Convergence with DP billing

Every user solves

$$\min_{\ell_n \in \mathcal{L}_n} \frac{E_n}{E} \sum_{t \in \mathcal{T}} C_t(\ell^t) \iff \min_{\ell_n \in \mathcal{L}_n} \sum_{t \in \mathcal{T}} C_t(\ell^t)$$

Alternate Minimization :

Theorem (Hong et al., 2017)

Alternate minimization on convex function f over N blocks converges linearly. Precisely, after r cycles:

$$f(x^{(r)}) - \min_{x \in \mathcal{X}} f(x) \le KN^2 \frac{1}{r}$$
.

 \Rightarrow Approximated $\varepsilon_r = \frac{\max E_n}{E} \frac{KN^2}{r}$ Nash Eq. in r cycles.

DP billing: each user solves

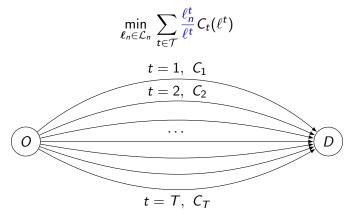
$$\min_{\ell_n \in \mathcal{L}_n} \frac{\frac{E_n}{E}}{E} \sum_{t \in \mathcal{T}} C_t(\ell^t)$$

HP billing: each user solves

$$\min_{\ell_n \in \mathcal{L}_n} \sum_{t \in \mathcal{T}} \frac{\ell_n^t}{\ell^t} C_t(\ell^t)$$

Convergence with HP billing

HP billing: each user solves



.

HP billing: each user solves

$$\min_{\ell_n \in \mathcal{L}_n} \sum_{t \in \mathcal{T}} \frac{\ell_n^t}{\ell^t} C_t(\ell^t)$$

Theorem (Orda et al., 1993)

In a network of parallel arcs with cost functions $\ell_n^t \mapsto \ell_n^t \times c_t(\ell^t)$, there exists a unique equilibrium.

HP billing: each user solves

$$\min_{\ell_n \in \mathcal{L}_n} \sum_{t \in \mathcal{T}} \frac{\frac{\ell_n^t}{\ell^t}}{\ell^t} C_t(\ell^t)$$

Theorem (Orda et al., 1993)

In a network of parallel arcs with cost functions $\ell_n^t \mapsto \ell_n^t \times c_t(\ell^t)$, there exists a unique equilibrium.

Proposition

The result extends to the constrained case $\underline{\ell_n^t} \leq \ell_n^t \leq \overline{\ell_n^t}$ (and where each player has a subset of arcs).

Convergence with HP billing (2)

In the case of quadratic costs $C_t(\ell^t) = a_t(\ell^t)^2 + b_t\ell^t$:

Convergence with HP billing (2)

In the case of quadratic costs $C_t(\ell^t) = a_t(\ell^t)^2 + b_t\ell^t$:

$$\min_{\ell_n \in \mathcal{L}_n} \sum_t \ell_n^t \times (a_t \ell^t + b_t)$$

Convergence with HP billing (2)

In the case of quadratic costs $C_t(\ell^t) = a_t(\ell^t)^2 + b_t\ell^t$:

$$\begin{split} \min_{\ell_n \in \mathcal{L}_n} \sum_t \ell_n^t \times (a_t \ell^t + b_t) \\ \Leftrightarrow \min_{\ell_n \in \mathcal{L}_n} \Phi(\ell) \end{split}$$

In the case of quadratic costs $C_t(\ell^t) = a_t(\ell^t)^2 + b_t\ell^t$:

$$\min_{\substack{\ell_n \in \mathcal{L}_n}} \sum_t \ell_n^t \times (a_t \ell^t + b_t)$$
$$\Leftrightarrow \min_{\ell_n \in \mathcal{L}_n} \Phi(\ell)$$

where $\Phi(\ell) = \sum_t \frac{a_t}{2} \left[(\ell^t)^2 + \sum_n (\ell_n^t)^2 \right] + b_t \ell^t$ is called a potential function:

In the case of quadratic costs $C_t(\ell^t) = a_t(\ell^t)^2 + b_t\ell^t$:

$$\min_{\substack{\ell_n \in \mathcal{L}_n}} \sum_t \ell_n^t \times (a_t \ell^t + b_t)$$
$$\Leftrightarrow \min_{\ell_n \in \mathcal{L}_n} \Phi(\ell)$$

where $\Phi(\ell) = \sum_t \frac{a_t}{2} \left[(\ell^t)^2 + \sum_n (\ell_n^t)^2 \right] + b_t \ell^t$ is called a potential function:

$$\forall n, \forall \ell_n, \ell'_n, \ell_{-n}, b_n(\ell_n, \ell_{-n}) - b_n(\ell'_n, \ell_{-n}) = \Phi(\ell_n, \ell_{-n}) - \Phi(\ell'_n, \ell_{-n})$$

In the case of quadratic costs $C_t(\ell^t) = a_t(\ell^t)^2 + b_t\ell^t$:

$$\min_{\ell_n \in \mathcal{L}_n} \sum_t \ell_n^t imes (a_t \ell^t + b_t) \ \Leftrightarrow \min_{\ell_n \in \mathcal{L}_n} \Phi(\ell)$$

where $\Phi(\ell) = \sum_t \frac{a_t}{2} \left[(\ell^t)^2 + \sum_n (\ell_n^t)^2 \right] + b_t \ell^t$ is called a potential function:

 $\forall n, \forall \ell_n, \ell'_n, \ell_{-n}, \ b_n(\ell_n, \ell_{-n}) - b_n(\ell'_n, \ell_{-n}) = \Phi(\ell_n, \ell_{-n}) - \Phi(\ell'_n, \ell_{-n}) \\ \iff \forall n, \forall \ell, \ \nabla_n b_n(\ell) = \nabla_n \Phi(\ell) .$

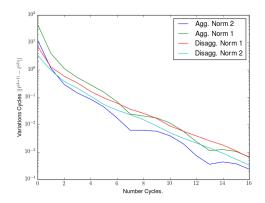
 $\bullet\,$ as before, alernate minimization on $\Phi\,$

- \bullet as before, alernate minimization on Φ
- the potential converges linearly to its minimum

- $\bullet\,$ as before, alernate minimization on $\Phi\,$
- the potential converges linearly to its minimum
- however, the rate of convergence of profiles is not clear..

- \bullet as before, alernate minimization on Φ
- the potential converges linearly to its minimum
- however, the rate of convergence of profiles is not clear..

Some hope numerically:



- \bullet as before, alernate minimization on Φ
- the potential converges linearly to its minimum
- however, the rate of convergence of profiles is not clear..

Conjecture (Brun et al., 2013) The non-linear spectral radius of CBRD operator: $\bar{\rho}(T_{BR}) = \lim \sup_{k \to \infty} \sup_{(A_i)_i \in \mathcal{J}(T_{BR})} \left\| \prod_{i=1}^k A_i \right\|^{1/k}$ is < 1 in a network of parallel arcs.

- \bullet as before, alernate minimization on Φ
- the potential converges linearly to its minimum
- however, the rate of convergence of profiles is not clear...

Conjecture (Brun et al., 2013)

The non-linear spectral radius of CBRD operator:

$$\bar{\rho}(T_{\mathsf{BR}}) = \limsup_{k \to \infty} \sup_{(A_i)_i \in \mathcal{J}(T_{\mathsf{BR}})} \left\| \prod_{i=1}^k A_i \right\|^{1/k}$$

is < 1 in a network of parallel arcs.

Corrolary: the BRD converges with an exponential rate.

With Demand Response, we reach an equilibrium profile...

With Demand Response, we reach an equilibrium profile...

... but how far from the optimal profile is it ?

NASH EQUILIBRIUM (NE) $(\ell_n)_n$ is a NE *IFF* for all *n*:

 $\forall \boldsymbol{\ell}'_n \in \mathcal{L}_n, \ b_n(\boldsymbol{\ell}_n, \boldsymbol{\ell}_{-n}) \leq b_n(\boldsymbol{\ell}'_n, \boldsymbol{\ell}_{-n})$

NASH EQUILIBRIUM (NE)
 $(\ell_n)_n$ is a NE IFF for all n:
 $\forall \ell'_n \in \mathcal{L}_n, \ b_n(\ell_n, \ell_{-n}) \leq b_n(\ell'_n, \ell_{-n})$ SOCIAL OPTIMUM (SO)
 $(\ell_n^*)_n$ is a SO IFF:
 $(\ell_n^*)_n = \operatorname{argmin}_n \sum_n b_n(\ell)$

NASH EQUILIBRIUM (NE)
 $(\ell_n)_n$ is a NE IFF for all n:
 $\forall \ell'_n \in \mathcal{L}_n, \ b_n(\ell_n, \ell_{-n}) \leq b_n(\ell'_n, \ell_{-n})$ SOCIAL OPTIMUM (SO)
 $(\ell_n^*)_n$ is a SO IFF:
 $(\ell_n^*)_n = \operatorname{argmin}_n \sum_n b_n(\ell)$

$$\begin{split} & \mathsf{Definition} \; (\mathsf{Price of Anarchy}) \\ & \mathsf{PoA}(\mathcal{G}) := \frac{\mathsf{sup}_{\ell \in \mathcal{X}^{\mathsf{NE}}_{\mathcal{G}}} \; \mathsf{SC}\left(\ell\right)}{\mathsf{SC}(\ell^*)} \; , \end{split}$$

where $SC(.) = \sum_{n} b_{n}(.)$ is the social cost.

• with Daily billing b_n^{DP} , every user minimizes $\frac{E_n}{E}SC$

 $\Rightarrow \mathsf{PoA} = 1$

3

• with *Daily* billing
$$b_n^{\text{DP}}$$
, every user minimizes $\frac{E_n}{E}$ SC

 $\Rightarrow \mathsf{PoA} = 1$

• with *Hourly* billing b_n^{HP} , the equilibrium is not optimal!

• with *Daily* billing
$$b_n^{DP}$$
, every user minimizes $\frac{E_n}{E}$ SC

 $\Rightarrow \mathsf{PoA} = 1$

• with *Hourly* billing b_n^{HP} , the equilibrium is not optimal!

Theorem

Assume costs are quadratic:

$$C_t(\ell) = a_1^t \ell + a_2^t \ell^2 ,$$

• with *Daily* billing
$$b_n^{DP}$$
, every user minimizes $\frac{E_n}{E}$ SC

 $\Rightarrow \mathsf{PoA} = 1$

• with *Hourly* billing b_n^{HP} , the equilibrium is not optimal!

Theorem

Assume costs are quadratic:

$$C_t(\ell) = a_1^t \ell + a_2^t \ell^2$$

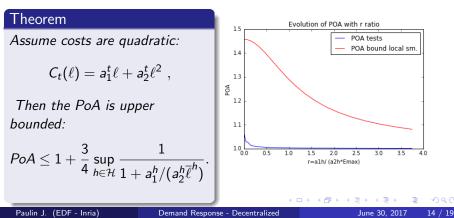
Then the PoA is upper bounded:

$$extsf{PoA} \leq 1 + rac{3}{4} \sup_{h \in \mathcal{H}} rac{1}{1 + a_1^h/(a_2^h \overline{\ell}^h)}.$$

• with *Daily* billing
$$b_n^{\text{DP}}$$
, every user minimizes $\frac{E_n}{E}$ SC

 $\Rightarrow \mathsf{PoA} = 1$

• with *Hourly* billing b_n^{HP} , the equilibrium is not optimal!



With linear costs, if for all n and for all t , $\ell_n^t > 0$:

$$PoA = 1 + \frac{\left(1 - \frac{4N}{(N+1)^2}\right)V}{-V + 8\left(\sum_{h}\frac{\alpha_h}{\beta_h}E + E^2\right)}$$

with
$$V \stackrel{\text{def}}{=} \sum_{k,h \in \mathcal{H}^2} \frac{(\alpha_k - \alpha_h)^2}{\beta_k \beta_h}$$
.

► < ∃ ►</p>

With linear costs, if for all n and for all t , $\ell_n^t > 0$:

$$PoA = 1 + \frac{\left(1 - \frac{4N}{(N+1)^2}\right)V}{-V + 8\left(\sum_{h}\frac{\alpha_h}{\beta_h}E + E^2\right)}$$

with
$$V \stackrel{\text{def}}{=} \sum_{k,h \in \mathcal{H}^2} \frac{(\alpha_k - \alpha_h)^2}{\beta_k \beta_h}$$
.

• Lower bound on the PoA...

-∢ ∃ ▶

With linear costs, if for all n and for all t , $\ell_n^t > 0$:

$$PoA = 1 + \frac{\left(1 - \frac{4N}{(N+1)^2}\right)V}{-V + 8\left(\sum_{h}\frac{\alpha_h}{\beta_h}E + E^2\right)}$$

with
$$V \stackrel{\text{def}}{=} \sum_{k,h \in \mathcal{H}^2} \frac{(\alpha_k - \alpha_h)^2}{\beta_k \beta_h}$$
.

- Lower bound on the PoA...
- ... but no upper bound!

э

With linear costs, if for all n and for all t , $\ell_n^t > 0$:

$$PoA = 1 + \frac{\left(1 - \frac{4N}{(N+1)^2}\right)V}{-V + 8\left(\sum_{h}\frac{\alpha_h}{\beta_h}E + E^2\right)}$$

with
$$V \stackrel{\text{def}}{=} \sum_{k,h \in \mathcal{H}^2} \frac{(\alpha_k - \alpha_h)^2}{\beta_k \beta_h}$$
.

- Lower bound on the PoA...
- … but no upper bound!
- Can we have some results in the nonlinear case ?

Consumers might have a prefered consumption profile $(\hat{\ell}_n^t)_t$

 \rightarrow distance to this profile will be penalized.

Consumers might have a prefered consumption profile $(\hat{\ell}_n^t)_t$

 \rightarrow distance to this profile will be penalized.

Assume user's objective is now:

$$f_n^{\alpha}(\boldsymbol{\ell_n}, \boldsymbol{\ell_{-n}}) = (1 - \alpha)b_n(\boldsymbol{\ell}) + \alpha \left\|\boldsymbol{\ell} - \hat{\boldsymbol{\ell}}\right\|_2^2$$

with $\alpha \in [0, 1]$ the preference factor.

Consumers might have a prefered consumption profile $(\hat{\ell}_n^t)_t$

 \rightarrow distance to this profile will be penalized.

Assume user's objective is now:

$$f_n^{\alpha}(\ell_n, \ell_{-n}) = (1 - \alpha)b_n(\ell) + \alpha \left\| \ell - \hat{\ell} \right\|_2^2 \qquad \text{s.t.} \qquad \sum_{t \in \mathcal{T}} \ell_n^t = E_n,$$

with $\alpha \in [0, 1]$ the preference factor.

t.
$$\sum_{t \in \mathcal{T}} \ell_n^t = E_n,$$
$$\underline{\ell}_n^t \le \underline{\ell}_n^t \le \overline{\ell}_n^t, \forall t$$

 $\min_{\boldsymbol{\ell}_n \in \mathbb{R}^T} \quad f_n^{\alpha}(\boldsymbol{\ell}_n, \boldsymbol{\ell}_{-n})$

Consumers might have a prefered consumption profile $(\hat{\ell}_n^t)_t$

 \rightarrow distance to this profile will be penalized.

Assume user's objective is now:

$$f_{n}^{\alpha}(\ell_{n}, \ell_{-n}) = (1 - \alpha)b_{n}(\ell) + \alpha \left\| \ell - \hat{\ell} \right\|_{2}^{2}$$
with $\alpha \in [0, 1]$ the preference factor.

$$\min_{\ell_{n} \in \mathbb{R}^{T}} f_{n}^{\alpha}(\ell_{n}, \ell_{-n})$$
s.t.

$$\sum_{t \in \mathcal{T}} \ell_{n}^{t} = E_{n},$$
 $\ell_{n}^{t} \leq \ell_{n}^{t} \leq \overline{\ell}_{n}^{t}, \forall t$

What is the impact on the equilibrium profile and global system costs ?

Assume: $T = \{P, O\}$, N users,

Assume: $\mathcal{T} = \{P, O\}$, N users, $C_t(\ell^t) = (\ell^t)^2$,

3

Assume: $\mathcal{T} = \{P, O\}$, N users, $C_t(\ell^t) = (\ell^t)^2$, $\ell_n^t \ge 0$.

3

Assume:
$$\mathcal{T} = \{P, O\}$$
, N users, $C_t(\ell^t) = (\ell^t)^2$, $\ell_n^t \ge 0$.

Proposition (Jacquot et al., 2017)

Assume $\forall n \in \mathcal{N}$, $\frac{\hat{\ell}_n^p}{E_n} + \frac{1}{2} \geq \frac{\hat{\ell}^p}{E}$, then, for $\alpha \in (0, 1]$, the NE of $\mathcal{G}_{\alpha}^{DP}$ gives:

 $\forall h \in \{P, O\}, \ \ell^h = E/2 + \alpha \times (\hat{\ell}^{\bar{h}} - \hat{\ell}^{\bar{h}})/2 \ . \tag{4}$

Assume:
$$\mathcal{T} = \{P, O\}$$
, N users, $C_t(\ell^t) = (\ell^t)^2$, $\ell_n^t \ge 0$.

Proposition (Jacquot et al., 2017)

Assume $\forall n \in \mathcal{N}$, $\frac{\hat{\ell}_n^p}{E_n} + \frac{1}{2} \geq \frac{\hat{\ell}^p}{E}$, then, for $\alpha \in (0, 1]$, the NE of $\mathcal{G}_{\alpha}^{DP}$ gives:

$$\forall h \in \{P, O\}, \ \ell^h = E/2 + \alpha \times (\hat{\ell}^{\bar{h}} - \hat{\ell}^{\bar{h}})/2 \ . \tag{4}$$

Proposition (Jacquot et al., 2017)

Assume $\forall n \in \mathcal{N}$, $\hat{\ell}_n^P \geq \frac{(\hat{\ell}^P - \hat{\ell}^O) - E_n}{2(N-1)}$, then $\forall \alpha \in [0, 1]$, the NE of $\mathcal{G}_{\alpha}^{HP}$ gives:

$$\forall h \in \{P, O\}, \ \ell^h = E/2 + \phi(\alpha) \times (\hat{\ell}^h - \hat{\ell}^{\bar{h}})/2 \ . \tag{5}$$

where $\phi(\alpha) \stackrel{\text{def}}{=} \frac{2\alpha}{(1+\alpha)+(1-\alpha)N} \in [0,1].$

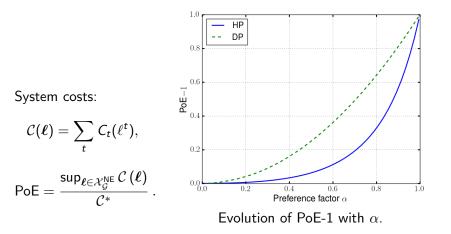
▲□▶ ▲圖▶ ▲ 圖▶ ▲ 圖▶ - 画 - のへ⊙

System costs:

$$\mathcal{C}(\boldsymbol{\ell}) = \sum_t C_t(\ell^t),$$

System costs:

$$\mathcal{C}(\ell) = \sum_{t} C_{t}(\ell^{t}),$$
$$\mathsf{PoE} = \frac{\sup_{\ell \in \mathcal{X}_{\mathcal{G}}^{\mathsf{NE}}} \mathcal{C}(\ell)}{\mathcal{C}^{*}}.$$



System costs:

$$C(\ell) = \sum_{t} C_t(\ell^t),$$
SUD $t = 2^{\text{INE}} C(\ell)$

$$\mathsf{PoE} = \frac{\mathsf{sup}_{\ell \in \mathcal{X}_{\mathcal{G}}^{\mathsf{NE}}} \mathcal{C}(\ell)}{\mathcal{C}^*}$$

.

Social Cost:

$$\mathrm{SC}(\ell) = \sum_n f_n^{lpha}(\ell)$$

System costs:

$$C(\ell) = \sum_{t} C_t(\ell^t),$$
SUD is a view $C(\ell)$

$$\mathsf{PoE} = \frac{\mathsf{sup}_{\ell \in \mathcal{X}_{\mathcal{G}}^{\mathsf{NE}}} \mathcal{C}(\ell)}{\mathcal{C}^{*}}$$

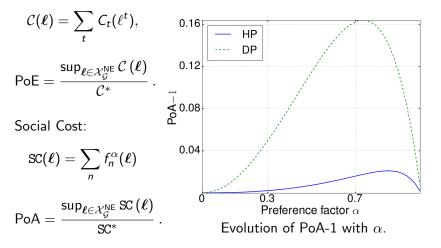
.

Social Cost:

$$SC(\ell) = \sum_n f_n^{\alpha}(\ell)$$

$$\mathsf{PoA} = rac{\mathsf{sup}_{\ell \in \mathcal{X}^{\mathsf{NE}}_{\mathcal{G}}}\,\mathsf{SC}\left(\ell
ight)}{\mathsf{SC}^{*}}\,.$$

System costs:



Two (complex!) problems:

Image: A math a math

Two (complex!) problems:

Need fast decentralized computation:

Fast convergence of BRD in network of parallel arcs ?

Two (complex!) problems:

- Need fast decentralized computation: Fast convergence of BRD in network of parallel arcs ?
- Need efficient equilibrium:

Can we compute tight bound on the PoA ?

Two (complex!) problems:

- Need fast decentralized computation: Fast convergence of BRD in network of parallel arcs ?
- Need efficient equilibrium:

Can we compute tight bound on the PoA ?

Other aspects and questions:

Two (complex!) problems:

- Need fast decentralized computation: Fast convergence of BRD in network of parallel arcs ?
- Need efficient equilibrium:

Can we compute tight bound on the PoA ?

Other aspects and questions:

• Non atomic (population) game model,

Two (complex!) problems:

- Need fast decentralized computation: Fast convergence of BRD in network of parallel arcs ?
- Need efficient equilibrium:

Can we compute tight bound on the PoA ?

Other aspects and questions:

- Non atomic (population) game model,
- Stochastic parameters (Energy demand can change..)

Two (complex!) problems:

- Need fast decentralized computation: Fast convergence of BRD in network of parallel arcs ?
- Need efficient equilibrium:

Can we compute tight bound on the PoA ?

Other aspects and questions:

- Non atomic (population) game model,
- Stochastic parameters (Energy demand can change..)

THANK YOU!

- [1] Brun, O., Prabhu, B. J., and Seregina, T. (2013). On the convergence of the best-response algorithm in routing games. In *Proceedings of the* 7th International Conference on Performance Evaluation Methodologies and Tools, pages 136–144. ICST (Institute for Computer Sciences, Social-Informatics and Telecommunications Engineering).
- [2] Hong, M., Wang, X., Razaviyayn, M., and Luo, Z.-Q. (2017). Iteration complexity analysis of block coordinate descent methods. *Mathematical Programming*, 163(1-2):85–114.
- [3] Jacquot, P., Beaude, O., Gaubert, S., and Oudjane, N. (2017).
 Demand response in the smart grid: the impact of consumers temporal preferences (submitted). In Smart Grid Communications (SmartGridComm), 2014 IEEE International Conference on. IEEE.
- [4] Orda, A., Rom, R., and Shimkin, N. (1993). Competitive routing in multiuser communication networks. *IEEE/ACM Transactions on Networking (ToN)*, 1(5):510–521.