Demand Response in the Smart Grid: the Impact of Consumers Temporal Preferences

### P. Jacquot <sup>1,2</sup> O.Beaude <sup>1</sup> S. Gaubert <sup>2</sup> N.Oudjane <sup>1</sup>

<sup>1</sup>EDF Lab Saclay

<sup>2</sup>Inria and CMAP, École Polytechnique

October 26, 2017



IEEE International Conference on Smart Grid Communications Dresden, Germany

















Each consumer *n* with flexible usages:



The aggregator has providing costs  $C_t(\ell^t)$ 







• convex and 
$$\nearrow$$
 in  $\ell^t = \sum_{n \in \mathcal{N}} \ell_n^t$ .





• convex and 
$$\nearrow$$
 in  $\ell^t = \sum_{n \in \mathcal{N}} \ell_n^t$ .





• convex and 
$$\nearrow$$
 in  $\ell^t = \sum_{n \in \mathcal{N}} \ell_n^t$ 

Each consumer *n* with flexible usages:



I minimizes its electricity bill



Each consumer *n* with flexible usages:



minimizes its electricity bill

and has a preferred consumption profile.



Each consumer *n* with flexible usages:



minimizes its electricity bill

and has a preferred consumption profile.

 $\rightarrow$  find a procedure that optimizes system costs AND users costs.

Each 
$$n \in \mathcal{N}$$
 minimizes a *bill* (signal) :  $\min_{\ell_n \in \mathcal{L}_n} b_n(\ell_n, \ell_{-n})$  subject to  $\begin{cases} \sum_t \ell_n^t = E_n \\ \underline{\ell}_n^t \leq \ell_n^t \leq \overline{\ell}_n^t, \forall t \end{cases}$ .

Each 
$$n \in \mathcal{N}$$
 minimizes a *bill* (signal) :  $\min_{\ell_n \in \mathcal{L}_n} b_n(\ell_n, \ell_{-n})$  subject to  $\begin{cases} \sum_t \ell_n^t = E_n \\ \underline{\ell}_n^t \leq \ell_n^t \leq \overline{\ell}_n^t, \forall t \end{cases}$ .

Depends on its own profile but also the profile chosen by the others

Each 
$$n \in \mathcal{N}$$
 minimizes a *bill* (signal) :  $\min_{\ell_n \in \mathcal{L}_n} b_n(\ell_n, \ell_{-n})$  subject to  $\begin{cases} \sum_t \ell_n^t = E_n \\ \underline{\ell}_n^t \leq \ell_n^t \leq \overline{\ell}_n^t, \forall t \end{cases}$ .

Depends on its own profile but also the profile chosen by the others  $\rightarrow$  GAME

Each 
$$n \in \mathcal{N}$$
 minimizes a *bill* (signal) :  $\min_{\ell_n \in \mathcal{L}_n} b_n(\ell_n, \ell_{-n})$  subject to  $\begin{cases} \sum_t \ell_n^t = E_n \\ \underline{\ell}_n^t \leq \ell_n^t \leq \overline{\ell}_n^t, \forall t \end{cases}$ .

Depends on its own profile but also the profile chosen by the others  $\rightarrow$  GAME

**Daily Proportional (DP)** [Mohsenian-Rad et al. (2010)]

$$b_n^{\mathrm{DP}}(\boldsymbol{\ell}_n, \boldsymbol{\ell}_{-n}) = \frac{\boldsymbol{E}_n}{\sum_{m \in \mathcal{N}} \boldsymbol{E}_m} \sum_{t \in \mathcal{T}} C_t \left( \sum_{m \in \mathcal{N}} \ell_m^t \right)$$

Each 
$$n \in \mathcal{N}$$
 minimizes a *bill* (signal) :  $\min_{\ell_n \in \mathcal{L}_n} b_n(\ell_n, \ell_{-n})$  subject to  $\begin{cases} \sum_t \ell_n^t = E_n \\ \underline{\ell}_n^t \leq \ell_n^t \leq \overline{\ell}_n^t, \forall t \end{cases}$ .

Depends on its own profile but also the profile chosen by the others  $\rightarrow$  GAME

**Daily Proportional (DP)** [Mohsenian-Rad et al. (2010)]

$$b_n^{\mathrm{DP}}(\ell_n, \ell_{-n}) = \frac{E_n}{\sum_{m \in \mathcal{N}} E_m} \sum_{t \in \mathcal{T}} C_t \left( \sum_{m \in \mathcal{N}} \ell_m^t \right)$$

Hourly Proportional (HP) [Baharlouei and Hashemi (2014), Jacquot et al. (2017)]

$$b_n^{\mathrm{HP}}(\ell_n, \ell_{-n}) = \sum_{t \in \mathcal{T}} \frac{\ell_n^t}{\sum_{m \in \mathcal{N}} \ell_m^t} C_t \left( \sum_{m \in \mathcal{N}} \ell_m^t \right)$$

Each 
$$n \in \mathcal{N}$$
 minimizes a *bill* (signal) :  $\min_{\ell_n \in \mathcal{L}_n} b_n(\ell_n, \ell_{-n})$  subject to  $\begin{cases} \sum_t \ell_n^t = E_n \\ \underline{\ell}_n^t \leq \ell_n^t \leq \overline{\ell}_n^t, \forall t \end{cases}$ .

Depends on its own profile but also the profile chosen by the others  $\rightarrow$  GAME

**Daily Proportional (DP)** [Mohsenian-Rad et al. (2010)]

$$b_n^{\mathrm{DP}}(\ell_n, \ell_{-n}) = \frac{E_n}{\sum_{m \in \mathcal{N}} E_m} \sum_{t \in \mathcal{T}} C_t \left( \sum_{m \in \mathcal{N}} \ell_m^t \right)$$

Hourly Proportional (HP) [Baharlouei and Hashemi (2014), Jacquot et al. (2017)]

$$b_n^{\mathrm{HP}}(\ell_n, \ell_{-n}) = \sum_{t \in \mathcal{T}} \frac{\ell_n^t}{\sum_{m \in \mathcal{N}} \ell_m^t} C_t \left( \sum_{m \in \mathcal{N}} \ell_m^t \right)$$

For HP and DP, system costs  $C(\ell) = \sum_t C_t(\ell^t)$  are equal to sum of users bills  $\sum_n b_n(\ell)$ .

In practice, consumers will not set their profile  $\ell_n$  to the optimum of  $b_n$ ,

In practice, consumers will not set their profile l<sub>n</sub> to the optimum of b<sub>n</sub>,
 Even if computation is automatic, they will disconnect if unhappy

- In practice, consumers will not set their profile l<sub>n</sub> to the optimum of b<sub>n</sub>,
   Even if computation is automatic, they will disconnect if unhappy
- $\rightarrow$  utility functions  $u_n(\ell_n)$

- In practice, consumers will not set their profile l<sub>n</sub> to the optimum of b<sub>n</sub>,
   Even if computation is automatic, they will disconnect if unhappy
- $\rightarrow$  utility functions  $u_n(\ell_n) = (\text{squarred})$  distance to a preferred profile  $\hat{\ell}_n$ :

$$u_n(\ell_n) := -\omega_n \sum_t (\ell_n^t - \hat{\ell}_n^t)^2$$

In practice, consumers will not set their profile l<sub>n</sub> to the optimum of b<sub>n</sub>,
 Even if computation is automatic, they will disconnect if unhappy

 $\rightarrow$  utility functions  $u_n(\ell_n) = (\text{squarred})$  distance to a preferred profile  $\hat{\ell}_n$ :

$$u_n(\ell_n) := -\omega_n \sum_t (\ell_n^t - \hat{\ell}_n^t)^2$$

 $\rightarrow$  define user's objective function as:

$$f_n^{\alpha}(\ell_n, \ell_{-n}) := b_n(\ell) - u_n(\ell_n)$$

In practice, consumers will not set their profile l<sub>n</sub> to the optimum of b<sub>n</sub>,
 Even if computation is automatic, they will disconnect if unhappy

 $\rightarrow$  utility functions  $u_n(\ell_n) = (\text{squarred})$  distance to a preferred profile  $\hat{\ell}_n$ :

$$u_n(\ell_n) := -\omega_n \sum_t (\ell_n^t - \hat{\ell}_n^t)^2$$

 $\rightarrow$  define user's objective function as:

$$f_n^{\alpha}(\ell_n, \ell_{-n}) := (1 - \alpha) b_n(\ell) - \alpha u_n(\ell_n)$$

with  $\alpha \in [0, 1]$  "preference factor".

In practice, consumers will not set their profile l<sub>n</sub> to the optimum of b<sub>n</sub>,
 Even if computation is automatic, they will disconnect if unhappy

ightarrow utility functions  $u_n(\ell_n)~=$  (squarred) distance to a preferred profile  $\hat{\ell}_n$ :

$$u_n(\ell_n) := -\omega_n \sum_t (\ell_n^t - \hat{\ell}_n^t)^2$$

 $\rightarrow$  define user's objective function as:

$$f_n^{\alpha}(\ell_n, \ell_{-n}) := (1 - \alpha) b_n(\ell) - \alpha u_n(\ell_n)$$

with  $\alpha \in [0, 1]$  "preference factor".

**Social Cost** SC( $\ell$ ) = sum of users objectives =  $\sum_{n \in \mathcal{N}} f_n^{\alpha}(\ell)$ .

In practice, consumers will not set their profile l<sub>n</sub> to the optimum of b<sub>n</sub>,
 Even if computation is automatic, they will disconnect if unhappy

ightarrow utility functions  $u_n(\ell_n)~=$  (squarred) distance to a preferred profile  $\hat{\ell}_n$ :

$$u_n(\ell_n) := -\omega_n \sum_t (\ell_n^t - \hat{\ell}_n^t)^2$$

 $\rightarrow$  define user's objective function as:

$$f_n^{\alpha}(\ell_n, \ell_{-n}) := (1 - \alpha) b_n(\ell) - \alpha u_n(\ell_n)$$

with  $\alpha \in [0, 1]$  "preference factor".

**Social Cost** SC( $\ell$ ) = sum of users objectives =  $\sum_{n \in \mathcal{N}} f_n^{\alpha}(\ell)$ .

 $b_n$  is either  $b_n^{\mathrm{HP}}$  or  $b_n^{\mathrm{DP}} \to \mathbf{2}$  games  $\mathcal{G}_{\alpha}^{\mathrm{HP}}$  and  $\mathcal{G}_{\alpha}^{\mathrm{DP}}$ .

In practice, consumers will not set their profile l<sub>n</sub> to the optimum of b<sub>n</sub>,
 Even if computation is automatic, they will disconnect if unhappy

 $\rightarrow$  utility functions  $u_n(\ell_n) = (\text{squarred})$  distance to a preferred profile  $\hat{\ell}_n$ :

$$u_n(\ell_n) := -\omega_n \sum_t (\ell_n^t - \hat{\ell}_n^t)^2$$

 $\rightarrow$  define user's objective function as:

$$f_n^{\alpha}(\ell_n, \ell_{-n}) := (1 - \alpha) b_n(\ell) - \alpha u_n(\ell_n)$$

with  $\alpha \in [0, 1]$  "preference factor".

**Social Cost** SC( $\ell$ ) = sum of users objectives =  $\sum_{n \in \mathcal{N}} f_n^{\alpha}(\ell)$ .

 $b_n$  is either  $b_n^{\mathrm{HP}}$  or  $b_n^{\mathrm{DP}} o \mathbf{2}$  games  $\mathcal{G}_{\alpha}^{\mathrm{HP}}$  and  $\mathcal{G}_{\alpha}^{\mathrm{DP}}$ .

How does the parameter  $\alpha$  influence the game ?

Paulin Jacquot (EDF - Inria)

We look for a stable situation where no user wants to change its profile

 $\rightarrow$  NASH EQUILIBRIUM (NE)

$$\mathcal{L}^{\mathsf{NE}}_lpha := \left\{ oldsymbol{\ell}^{\operatorname{NE}} \in \mathcal{L}: ext{ for each } n, oldsymbol{\ell}^{\operatorname{NE}}_n \in lpha \operatorname{rgmin}_{oldsymbol{\ell}_n \in \mathcal{L}_n} f^lpha_n(oldsymbol{\ell}_n, oldsymbol{\ell}^{\operatorname{NE}}_{-n}) 
ight\}.$$

We look for a stable situation where no user wants to change its profile

#### $\rightarrow$ NASH EQUILIBRIUM (NE)

$$\mathcal{L}^{\mathsf{NE}}_{\alpha} := \left\{ \boldsymbol{\ell}^{\mathrm{NE}} \in \mathcal{L}: \text{ for each } n, \boldsymbol{\ell}^{\mathrm{NE}}_n \in \arg\min_{\boldsymbol{\ell}_n \in \mathcal{L}_n} f^{\alpha}_n(\boldsymbol{\ell}_n, \boldsymbol{\ell}^{\mathrm{NE}}_{-n}) \right\}.$$

#### Theorem

With any  $\alpha \in [0,1]$  and costs  $C_t(\ell) = a_t \ell + b_t \ell^2$ , for the games  $\mathcal{G}_{\alpha}^{\mathrm{DP}} = (\mathcal{N}, \mathcal{L}, (f_n^{\alpha})_n))$  and  $\mathcal{G}_{\alpha}^{\mathrm{HP}} = (\mathcal{N}, \mathcal{L}, (f_n^{\alpha})_n))$ , the following results hold:

each game has a unique Nash Equilibrum,

the Best Response Dynamics (sequential alternating minimization) converges to each NE.

We look for a stable situation where no user wants to change its profile

#### $\rightarrow$ NASH EQUILIBRIUM (NE)

$$\mathcal{L}^{\mathsf{NE}}_{\alpha} := \left\{ \boldsymbol{\ell}^{\mathrm{NE}} \in \mathcal{L}: \text{ for each } n, \boldsymbol{\ell}^{\mathrm{NE}}_n \in \arg\min_{\boldsymbol{\ell}_n \in \mathcal{L}_n} f^{\alpha}_n(\boldsymbol{\ell}_n, \boldsymbol{\ell}^{\mathrm{NE}}_{-n}) \right\}.$$

#### Theorem

With any  $\alpha \in [0,1]$  and costs  $C_t(\ell) = a_t \ell + b_t \ell^2$ , for the games  $\mathcal{G}_{\alpha}^{\mathrm{DP}} = (\mathcal{N}, \mathcal{L}, (f_n^{\alpha})_n))$  and  $\mathcal{G}_{\alpha}^{\mathrm{HP}} = (\mathcal{N}, \mathcal{L}, (f_n^{\alpha})_n))$ , the following results hold:

each game has a unique Nash Equilibrum,

the Best Response Dynamics (sequential alternating minimization) converges to each NE.

**Remark 1:** this is obtained by showing that the Games have the "potential" property.

We look for a stable situation where no user wants to change its profile

#### $\rightarrow$ NASH EQUILIBRIUM (NE)

$$\mathcal{L}^{\mathsf{NE}}_{\alpha} := \left\{ \boldsymbol{\ell}^{\mathrm{NE}} \in \mathcal{L}: \text{ for each } n, \boldsymbol{\ell}^{\mathrm{NE}}_n \in \arg\min_{\boldsymbol{\ell}_n \in \mathcal{L}_n} f^{\alpha}_n(\boldsymbol{\ell}_n, \boldsymbol{\ell}^{\mathrm{NE}}_{-n}) \right\}.$$

#### Theorem

With any  $\alpha \in [0,1]$  and costs  $C_t(\ell) = a_t \ell + b_t \ell^2$ , for the games  $\mathcal{G}_{\alpha}^{\mathrm{DP}} = (\mathcal{N}, \mathcal{L}, (f_n^{\alpha})_n))$  and  $\mathcal{G}_{\alpha}^{\mathrm{HP}} = (\mathcal{N}, \mathcal{L}, (f_n^{\alpha})_n))$ , the following results hold:

each game has a unique Nash Equilibrum,

the Best Response Dynamics (sequential alternating minimization) converges to each NE.

Remark 1: this is obtained by showing that the Games have the "potential" property.Remark 2: The BRD provides a decentralized algorithm to compute each equilibrium.

PRICE OF ANARCHY, (Koutsoupias and Papadimitriou, 1999) Define  $SC(\ell) = \sum_{n} f_n(\ell)$  the **Social Cost** and  $SC^*$  the optimal social cost.

PRICE OF ANARCHY, (Koutsoupias and Papadimitriou, 1999) Define  $SC(\ell) = \sum_n f_n(\ell)$  the **Social Cost** and  $SC^*$  the optimal social cost. A usual indicator to measure the efficiency of the NE is the PoA:

$$\mathsf{PoA}(\mathcal{G}) := \left(\mathsf{sup}_{\boldsymbol{\ell} \in \mathcal{L}^{\mathsf{NE}}_{\mathcal{G}}} \operatorname{SC}\left(\boldsymbol{\ell}\right)
ight) / \operatorname{SC}^{*}$$
 .

PRICE OF ANARCHY, (Koutsoupias and Papadimitriou, 1999) Define  $SC(\ell) = \sum_n f_n(\ell)$  the **Social Cost** and  $SC^*$  the optimal social cost. A usual indicator to measure the efficiency of the NE is the PoA:

$$\mathsf{PoA}(\mathcal{G}) := \left(\mathsf{sup}_{\boldsymbol{\ell} \in \mathcal{L}^{\mathsf{NE}}_{\mathcal{G}}} \operatorname{SC}(\boldsymbol{\ell}) \right) / \operatorname{SC}^{*}$$
 .

#### PRICE OF EFFICIENCY

We define a similar quantity from the system side, without the users preferences, but only considering the system costs  $C(\ell) := \sum_{t \in \mathcal{T}} C_t(\ell^t)$ :

$$\mathsf{PoE}(\mathcal{G}) := \left(\mathsf{sup}_{\boldsymbol{\ell} \in \mathcal{L}^{\mathsf{NE}}_{\mathcal{G}}} \, \mathcal{C}\left(\boldsymbol{\ell}\right)\right) / \, \mathcal{C}^* \, \, .$$

PRICE OF ANARCHY, (Koutsoupias and Papadimitriou, 1999) Define  $SC(\ell) = \sum_n f_n(\ell)$  the **Social Cost** and  $SC^*$  the optimal social cost. A usual indicator to measure the efficiency of the NE is the PoA:

$$\mathsf{PoA}(\mathcal{G}) := \left(\mathsf{sup}_{\boldsymbol{\ell} \in \mathcal{L}^{\mathsf{NE}}_{\mathcal{G}}} \operatorname{SC}(\boldsymbol{\ell}) \right) / \operatorname{SC}^{*}$$
 .

#### PRICE OF EFFICIENCY

We define a similar quantity from the system side, without the users preferences, but only considering the system costs  $C(\ell) := \sum_{t \in \mathcal{T}} C_t(\ell^t)$ :

$$\mathsf{PoE}(\mathcal{G}) := \left( \mathsf{sup}_{\ell \in \mathcal{L}^{\mathsf{NE}}_{\mathcal{G}}} \mathcal{C}\left(\ell\right) \right) / \mathcal{C}^* \;.$$

**Remark**:

1. For 
$$\alpha = 0$$
,  $\mathsf{PoE}(\mathcal{G}_{\alpha}) = \mathsf{PoA}(\mathcal{G}_{\alpha})$ .

PoA > 1 and PoE >

$$\blacksquare \ \mathcal{T} = \{O, P\},\$$

■ 
$$\mathcal{T} = \{O, P\},$$
  
■  $\forall t \in \{O, P\}, \ C_t(\ell) = \ell^2,$ 

■ 
$$\mathcal{T} = \{O, P\},$$
  
■  $\forall t \in \{O, P\}, \ C_t(\ell) = \ell^2,$ 

■ preferences:  $\sum_{n} \hat{\ell}_{n}^{P} = \hat{\ell}^{P} > \frac{E}{2} > \hat{\ell}^{O} = \sum_{n} \hat{\ell}_{n}^{O}.$ 

$$T = \{O, P\},$$
  
$$\forall t \in \{O, P\}, C_t(\ell) = \ell^2,$$
  
preferences:

$$\sum_{n} \hat{\ell}_{n}^{P} = \hat{\ell}^{P} > \frac{E}{2} > \hat{\ell}^{O} = \sum_{n} \hat{\ell}_{n}^{O}.$$

#### Theorem

Under certain conditions on  $\hat{\ell}_n$  and  $(E_n)_n$ , the unique NE are given, for  $\alpha \in [0,1]$  by:

for 
$$\mathcal{G}_{\alpha}^{DP}$$
,  $\ell^{P} = \frac{E}{2} + \alpha \frac{(\ell^{P} - \hat{\ell}^{O})}{2}$ ,  
for  $\mathcal{G}_{\alpha}^{HP}$ ,  $\ell^{P} = \frac{E}{2} + \phi(\alpha) \frac{(\ell^{P} - \hat{\ell}^{O})}{2}$ .

with: 
$$\phi(lpha) \stackrel{def}{=} rac{2lpha}{(1+lpha)+(1-lpha)\mathsf{N}} \in [0,1]$$
 .

 $\blacksquare \ \mathcal{T} = \{O, P\},$ 

$$lacksquare$$
  $orall t\in\{O,P\},\ C_t(\ell)=\ell^2$  ,

preferences:  $\sum_{n} \hat{\ell}_{n}^{P} = \hat{\ell}^{P} > \frac{E}{2} > \hat{\ell}^{O} = \sum_{n} \hat{\ell}_{n}^{O}.$ 

#### Theorem

Under certain conditions on  $\hat{\ell}_n$  and  $(E_n)_n$ , the unique NE are given, for  $\alpha \in [0,1]$  by:

for 
$$\mathcal{G}_{\alpha}^{DP}$$
,  $\ell^{P} = \frac{E}{2} + \alpha \frac{(\ell^{P} - \hat{\ell}^{O})}{2}$ ,  
for  $\mathcal{G}_{\alpha}^{HP}$ ,  $\ell^{P} = \frac{E}{2} + \phi(\alpha) \frac{(\ell^{P} - \hat{\ell}^{O})}{2}$ .

with: 
$$\phi(lpha) \stackrel{def}{=} rac{2lpha}{(1+lpha)+(1-lpha)\mathsf{N}} \in [0,1]$$
 .

Paulin Jacquot (EDF - Inria)

 $\rightarrow$  Explicit System costs and PoE at NE

 $\blacksquare \ \mathcal{T} = \{O, P\},$ 

$$\forall t \in \{O,P\}, \ C_t(\ell) = \ell^2$$
 ,

preferences:  $\sum_{n} \hat{\ell}_{n}^{P} = \hat{\ell}^{P} > \frac{E}{2} > \hat{\ell}^{O} = \sum_{n} \hat{\ell}_{n}^{O}.$ 

#### Theorem

Under certain conditions on  $\hat{\ell}_n$  and  $(E_n)_n$ , the unique NE are given, for  $\alpha \in [0, 1]$  by:

$$\begin{array}{l} \text{for } \mathcal{G}_{\alpha}^{DP}, \ \ell^{P} = \frac{E}{2} + \alpha \frac{(\ell^{P} - \hat{\ell}^{O})}{2} \ , \\ \text{for } \mathcal{G}_{\alpha}^{HP}, \ \ell^{P} = \frac{E}{2} + \phi(\alpha) \frac{(\ell^{P} - \hat{\ell}^{O})}{2} \ . \end{array}$$

with: 
$$\phi(lpha) \stackrel{def}{=} rac{2lpha}{(1+lpha)+(1-lpha)N} \in [0,1]$$
 .

 $\begin{array}{l} \rightarrow \text{ Explicit System costs and PoE at NE} \\ \text{THM: } \forall \alpha \in [0,1], \mathsf{PoE}(\mathcal{G}^{\mathsf{HP}}_{\alpha}) \leq \mathsf{PoE}(\mathcal{G}^{\mathsf{DP}}_{\alpha}). \end{array}$ 

$$\blacksquare \ \mathcal{T} = \{O, P\},$$

$$\forall t \in \{O, P\}, \ C_t(\ell) = \ell^2$$
 ,

preferences:  $\sum_{n} \hat{\ell}_{n}^{P} = \hat{\ell}^{P} > \frac{E}{2} > \hat{\ell}^{O} = \sum_{n} \hat{\ell}_{n}^{O}.$ 

#### Theorem

Under certain conditions on  $\hat{\ell}_n$  and  $(E_n)_n$ , the unique NE are given, for  $\alpha \in [0, 1]$  by:

$$\begin{array}{l} \text{for } \mathcal{G}_{\alpha}^{DP}, \ \ell^{P} = \frac{E}{2} + \alpha \frac{(\hat{\ell}^{P} - \hat{\ell}^{O})}{2} \ , \\ \text{for } \mathcal{G}_{\alpha}^{HP}, \ \ell^{P} = \frac{E}{2} + \phi(\alpha) \frac{(\hat{\ell}^{P} - \hat{\ell}^{O})}{2} \end{array}$$

with: 
$$\phi(lpha) \stackrel{\mathsf{def}}{=} rac{2lpha}{(1+lpha)+(1-lpha)\mathsf{N}} \in [0,1]$$
 .

→ Explicit System costs and PoE at NE THM:  $\forall \alpha \in [0, 1], \mathsf{PoE}(\mathcal{G}_{\alpha}^{\mathsf{HP}}) \leq \mathsf{PoE}(\mathcal{G}_{\alpha}^{\mathsf{DP}}).$ 



 $\blacksquare \ \mathcal{T} = \{O, P\},$ 

$$\forall t \in \{O,P\}, \ C_t(\ell) = \ell^2$$
 ,

preferences:  $\sum_{n} \hat{\ell}_{n}^{P} = \hat{\ell}^{P} > \frac{E}{2} > \hat{\ell}^{O} = \sum_{n} \hat{\ell}_{n}^{O}.$ 

#### Theorem

Under certain conditions on  $\hat{\ell}_n$  and  $(E_n)_n$ , the unique NE are given, for  $\alpha \in [0, 1]$  by:

$$\begin{array}{l} \text{for } \mathcal{G}_{\alpha}^{DP}, \ \ell^{P} = \frac{E}{2} + \alpha \frac{(\hat{\ell}^{P} - \hat{\ell}^{O})}{2} \ , \\ \text{for } \mathcal{G}_{\alpha}^{HP}, \ \ell^{P} = \frac{E}{2} + \phi(\alpha) \frac{(\hat{\ell}^{P} - \hat{\ell}^{O})}{2} \end{array}$$

with: 
$$\phi(lpha) \stackrel{\mathsf{def}}{=} rac{2lpha}{(1+lpha)+(1-lpha)\mathsf{N}} \in [0,1]$$
 .

 $\begin{array}{l} \rightarrow \text{ Explicit System costs and PoE at NE} \\ \text{THM: } \forall \alpha \in [0,1], \mathsf{PoE}(\mathcal{G}^{\mathsf{HP}}_{\alpha}) \leq \mathsf{PoE}(\mathcal{G}^{\mathsf{DP}}_{\alpha}). \end{array}$ 



$$\blacksquare \mathcal{T} = \{O, P\},$$

$$lacksquare$$
  $orall t\in\{O,P\},\ C_t(\ell)=\ell^2$  ,

preferences:  $\sum_{n} \hat{\ell}_{n}^{P} = \hat{\ell}^{P} > \frac{E}{2} > \hat{\ell}^{O} = \sum_{n} \hat{\ell}_{n}^{O}.$ 

#### Theorem

Under certain conditions on  $\hat{\ell}_n$  and  $(E_n)_n$ , the unique NE are given, for  $\alpha \in [0, 1]$  by:

$$\begin{array}{l} \text{for } \mathcal{G}^{DP}_{\alpha}, \ \ell^{P} = \frac{E}{2} + \alpha \frac{(\hat{\ell}^{P} - \hat{\ell}^{O})}{2} \ , \\ \text{for } \mathcal{G}^{HP}_{\alpha}, \ \ell^{P} = \frac{E}{2} + \phi(\alpha) \frac{(\hat{\ell}^{P} - \hat{\ell}^{O})}{2} \end{array}$$

with: 
$$\phi(lpha) \stackrel{\mathsf{def}}{=} rac{2lpha}{(1+lpha)+(1-lpha)\mathsf{N}} \in [0,1]$$
 .

→ Explicit System costs and PoE at NE THM:  $\forall \alpha \in [0, 1], \mathsf{PoE}(\mathcal{G}^{\mathsf{HP}}_{\alpha}) \leq \mathsf{PoE}(\mathcal{G}^{\mathsf{DP}}_{\alpha}).$ 



Example on 2016/01/10:

 $\alpha = \mathbf{0.0}$ 



Example on 2016/01/10:

 $\alpha = \textbf{0.001}$ 



Example on 2016/01/10:

 $\alpha = 0.002$ 



Example on 2016/01/10:





Example on 2016/01/10:





Example on 2016/01/10:

 $\alpha = 0.005$ 



Example on 2016/01/10:





### Simulation with 30 users on a real database

Simulation on DR on all days of January 2016.

Example on 2016/01/10:

 $\alpha = 0.03$ 



### Simulation with 30 users on a real database

Simulation on DR on all days of January 2016.

Example on 2016/01/10:

 $\alpha = 1.0$ 



#### **Price of Anarchy**



```
\mathcal{D} = \{ \text{all days of January, 2016} \}.
```

for  $\alpha = 0$ , DP is optimal but HP has very small PoA (=1.0015) (see [2]),

#### **Price of Anarchy**



 $<sup>\</sup>mathcal{D} = \{ \text{all days of January, 2016} \}.$ 

for  $\alpha = 0$ , DP is optimal but HP has very small PoA (=1.0015) (see [2]),

when  $\alpha$  grows, HP is more efficient than DP,  $\max_{\alpha} \operatorname{PoA}(\mathcal{G}^{\mathrm{DP}}_{\alpha}) = 1.122$ ,

#### **Price of Efficiency**



- for  $\alpha = 0$ , DP is optimal but HP has very small PoA (=1.0015) (see [2]),
- when  $\alpha$  grows, HP is more efficient than DP,  $\max_{\alpha} \operatorname{PoA}(\mathcal{G}^{\mathrm{DP}}_{\alpha}) = 1.122$ ,
- PoE is lower for a wide range of  $\alpha$   $\rightarrow$  users will be more selfish with the DP billing, less robust,

#### **Price of Efficiency**



for  $\alpha = 0$ , DP is optimal but HP has very small PoA (=1.0015) (see [2]),

- when  $\alpha$  grows, HP is more efficient than DP,  $\max_{\alpha} \operatorname{PoA}(\mathcal{G}^{\mathrm{DP}}_{\alpha}) = 1.122$ ,
- PoE is lower for a wide range of  $\alpha$   $\rightarrow$  users will be more selfish with the DP billing, less robust,
- HP will be more beneficial for the aggregator.

Game-theoretic model for DR integrating users temporal preferences.

Game-theoretic model for DR integrating users temporal preferences.
 With preferences, HP billing performs better than DP.

Game-theoretic model for DR integrating users temporal preferences.
 With preferences, HP billing performs better than DP.

An implementation of Demand Response based on the HP billing is interesting both for consumers and for the system, and we have a distributed algorithm to compute load profiles.

Game-theoretic model for DR integrating users temporal preferences.
 With preferences, HP billing performs better than DP.

An implementation of Demand Response based on the HP billing is interesting both for consumers and for the system, and we have a distributed algorithm to compute load profiles.

In practice  $\alpha$  could differ among price-sensitive users, and is difficult to estimate.

Game-theoretic model for DR integrating users temporal preferences.
 With preferences, HP billing performs better than DP.

An implementation of Demand Response based on the HP billing is interesting both for consumers and for the system, and we have a distributed algorithm to compute load profiles.

In practice  $\alpha$  could differ among price-sensitive users, and is difficult to estimate.

**Extension**: preferences could be used in a dynamic model where users can leave the DR program if unsatisfied.

Game-theoretic model for DR integrating users temporal preferences.
 With preferences, HP billing performs better than DP.

An implementation of Demand Response based on the HP billing is interesting both for consumers and for the system, and we have a distributed algorithm to compute load profiles.

In practice  $\alpha$  could differ among price-sensitive users, and is difficult to estimate.

**Extension**: preferences could be used in a dynamic model where users can leave the DR program if unsatisfied.

# THANK YOU!

paulin.jacquot@polytechnique.edu

- [1] Baharlouei, Z. and Hashemi, M. (2014). Efficiency-fairness trade-off in privacy-preserving autonomous demand side management. *IEEE Transactions on Smart Grid*, 5(2):799–808.
- [2] Jacquot, P., Beaude, O., Gaubert, S., and Oudjane, N. (2017). Demand side management in the smart grid: an efficiency and fairness tradeoff (accepted). In *Innovative Smart Grid Technologies (ISGT), 2017 IEEE PES.* IEEE.
- [3] Koutsoupias, E. and Papadimitriou, C. (1999). Worst-case equilibria. In Annual Symposium on Theoretical Aspects of Computer Science, pages 404–413. Springer.
- [4] Mohsenian-Rad, A.-H., Wong, V. W., Jatskevich, J., Schober, R., and Leon-Garcia, A. (2010). Autonomous demand-side management based on game-theoretic energy consumption scheduling for the future smart grid. *IEEE transactions on Smart Grid*, 1:320–331.